

# Comment relâcher la contrainte de trame ajustée dans le cadre des méthodes proximales en restauration d'images?

Nelly Pustelnik<sup>(1)</sup>, Jean-Christophe Pesquet<sup>(2)</sup> et Caroline Chaux<sup>(2)</sup>

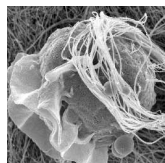
(1) Lab. IMS – Université Bordeaux 1

(2) Lab. IGM - Université Paris-Est

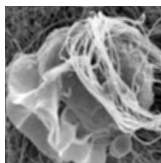
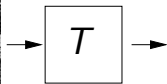
GdR ISIS : 1er Avril 2011



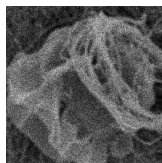
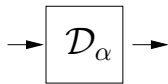
## Degradation model: convolution and noise



Original image  
 $\bar{y} \in \ell^2(\mathbb{Z})$



Blurred image ( $T\bar{y}$ )



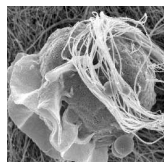
Degraded image  
 $z \in \ell^2(\mathbb{Z})$   
 $\alpha = 0.1$

Degradation model

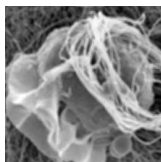
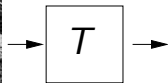
$$z = \mathcal{D}_\alpha(T\bar{y})$$

- ▶  $T: \ell^2(\mathbb{Z}) \rightarrow \ell^2(\mathbb{Z})$ : Convolution operator
- ▶  $\mathcal{D}_\alpha$ : Effect of noise (Gaussian noise, Poisson noise, Laplace noise, ...)
- ▶  $\alpha$ : noise parameter (variance for Gaussian noise, scaling parameter for Poisson noise, ...)

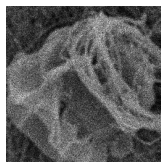
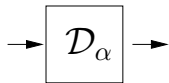
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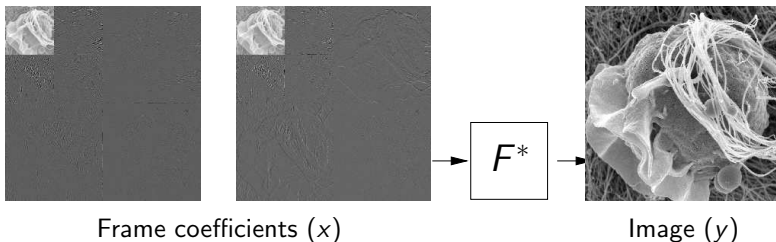
⇒ Our objective is to recover an image  $\hat{y}$ , the closest as possible to  $\bar{y}$ .

## Existing wavelet-based variational methods

### Gaussian noise + convolution

- ▶ Quadratic regularization techniques (Wiener filtering).
- ▶ Multiresolution analyses were used for denoising ( $T = \text{Id}$ ).
- ▶ Redundant **frame representations** were substituted for wavelet bases for denoising.

## Frame representation

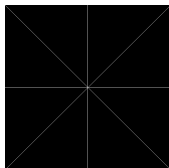


- ▶  $x \in \ell^2(\mathbb{Z})$ : **Frame coefficients** of the image  $y$ .
- ▶  $F^*: \ell^2(\mathbb{Z}) \rightarrow \ell^2(\mathbb{Z})$ : **Frame synthesis operator**

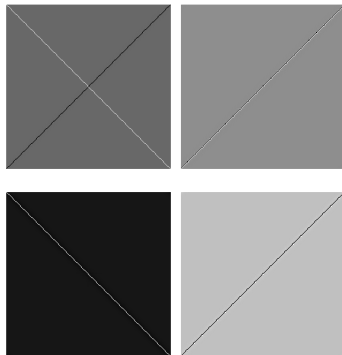
$$y = F^* x$$

- ▶  $F: \ell^2(\mathbb{Z}) \rightarrow \ell^2(\mathbb{Z})$ : **Frame analysis operator**
- ▶ Frame is **tight** if  $\exists \mu \in ]0, +\infty[$ ,  $F^* F = \mu \text{Id}$ .

## Tight frame drawback: DTT example



Original



Diagonal decomposition coefficients  
for the first resolution level  
without prefiltering (top) and with prefiltering (bottom)  
after a dual-tree decomposition  
with Meyer filter  $M = 2$ .

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### Laplace, Poisson, ... noise + convolution

- ▶ Douglas-Rachford (DR) algorithm [Combettes&Pesquet 2007]
- ▶ Parallel Proximal Algo. (PPXA) [Combettes&Pesquet 2008]
- ▶ ADMM [Afonso et al. 2009, Setzer et al. 2009]
- ▶ PPXA+: unifying framework for PPXA and ADMM [Pesquet 2010]

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## Considered problems

### Synthesis formulation (SF):

$$\hat{y} = F^* \hat{x} \quad \text{such that} \quad \hat{x} \in \underset{x \in \ell^2(\mathbb{Z})}{\text{Argmin}} \sum_{i=1}^n f_i(L_i F^* x) + \sum_{j=1}^m g_j(x)$$

### Analysis formulation (AF):

$$\hat{y} \in \underset{y \in \ell^2(\mathbb{Z})}{\text{Argmin}} \sum_{i=1}^n f_i(L_i y) + \sum_{j=1}^m g_j(F y)$$

- ▶ For every  $i \in \{1, \dots, n\}$ ,  $f_i: \ell^2(\mathbb{Z}) \mapsto ]-\infty, +\infty]$  is a convex, l.s.c and proper function and  $L_i: \ell^2(\mathbb{Z}) \rightarrow \ell^2(\mathbb{Z})$  is a convolutive operator.
- ▶ For every  $j \in \{1, \dots, m\}$ ,  $g_j: \ell^2(\mathbb{Z}) \mapsto ]-\infty, +\infty]$  is a convex, l.s.c and proper function.

## Proximity operator

### Definition [Moreau (1965)]

- **Definition:** For every  $u$  in a Hilbert space  $\mathcal{H}$ , the function  $v \mapsto \varphi(v) + \|u - v\|^2/2$ , where  $\varphi$  is a convex, l.s.c and proper function, achieves its minimum at a **unique point** denoted by  $\text{prox}_\varphi u$ , i.e.,

$$(\forall u \in \mathcal{H}),$$

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### Examples:

- If  $\varphi = \iota_C \Rightarrow \text{prox}_{\iota_C} = P_C$  where  $\iota_C$  denotes the indicator function over a closed convex set  $C$  and  $P_C$  denotes the projection onto  $C$
- If  $\varphi = \chi|\cdot|$  with  $\chi > 0 \Rightarrow \text{prox}_{\chi|\cdot|}$  is a **soft-thresholding** with threshold value  $\chi$
- If  $\varphi = \omega|\cdot|^p + \chi|\cdot|$  with  $\omega > 0 \Rightarrow$  **Closed forms for several  $p \geq 1$**

$$\text{PPXA+}: \underset{x \in \ell^2(\mathbb{Z})}{\text{minimize}} \sum_{i=1}^n f_i(L_i F^* x) + \sum_{j=1}^m g_j(x)$$

Initialization

$$\left[ \begin{array}{l} (\eta_i)_{1 \leq i \leq n} \in ]0, +\infty[^n, (\kappa_j)_{1 \leq j \leq m} \in ]0, +\infty[^m \\ (v_{i,0})_{1 \leq i \leq n} \in (\ell^2(\mathbb{Z}))^n, (w_{j,0})_{1 \leq j \leq m} \in (\ell^2(\mathbb{Z}))^m \\ x_0 = \arg \min_{u \in \ell^2(\mathbb{Z})} \sum_{i=1}^n \eta_i \|L_i F^* u - v_{i,0}\|^2 + \sum_{j=1}^m \kappa_j \|u - w_{j,0}\|^2 \end{array} \right.$$

For  $\ell = 0, 1, \dots$

$$\left[ \begin{array}{l} \text{For } i = 1, \dots, n \\ \quad \lfloor p_{i,\ell} = \text{prox}_{f_i/\eta_i} v_{i,\ell} \\ \text{For } j = 1, \dots, m \\ \quad \lfloor r_{j,\ell} = \text{prox}_{g_j/\kappa_j} w_{j,\ell} \\ \lambda_\ell \in ]0, 2[ \\ c_\ell = \arg \min_{u \in \ell^2(\mathbb{Z})} \sum_{i=1}^n \eta_i \|L_i F^* u - p_{i,\ell}\|^2 + \sum_{j=1}^m \kappa_j \|u - r_{j,\ell}\|^2 \\ \text{For } i = 1, \dots, n \\ \quad \lfloor v_{i,\ell+1} = v_{i,\ell} + \lambda_\ell (L_i F^* (2c_\ell - x_\ell) - p_{i,\ell}) \\ \text{For } j = 1, \dots, m \\ \quad \lfloor w_{j,\ell+1} = w_{j,\ell} + \lambda_\ell (2c_\ell - x_\ell - r_{j,\ell}) \\ x_{\ell+1} = x_\ell + \lambda_\ell (c_\ell - x_\ell) \end{array} \right.$$

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## PPXA+ convergence

The convergence of the sequence  $(x_\ell)_{\ell \in \mathbb{N}}$  (resp.  $(y_\ell)_{\ell \in \mathbb{N}}$ ) generated by algorithm PPXA+ for SF (resp. algorithm PPXA+ for AF) is established under the following assumptions:

- $\left( \bigcap_{i=1}^n \text{ri dom } f_i \circ L_i F^* \right) \cap \left( \bigcap_{j=1}^m \text{ri dom } g_j \right) \neq \emptyset$   
(resp.  $\left( \bigcap_{i=1}^n \text{ri dom } f_i \circ L_i \right) \cap \left( \bigcap_{j=1}^m \text{ri dom } g_j \circ F \right) \neq \emptyset$ ).
- There exists  $\underline{\lambda} \in ]0, 2[$  such that  $(\forall \ell \in \mathbb{N}), \underline{\lambda} \leq \lambda_{\ell+1} \leq \lambda_\ell$ .

## Difficulties to use PPXA+ and frame representations

- Analysis formulation

**PPXA+ iteration:**

$$c_\ell = \left( \sum_{i=1}^n \eta_i L_i^* L_i + \sum_{j=1}^m \kappa_j F^* F \right)^{-1} \left( \sum_{i=1}^n \eta_i L_i^* p_{i,\ell} + \sum_{j=1}^m \kappa_j F^* r_{j,\ell} \right)$$

- Synthesis formulation

**PPXA+ iteration:**

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**Difficulty:**

$$\left( \sum_{i=1}^n \eta_i L_i^* L_i + \kappa F^* F \right)^{-1} \quad \text{by setting} \quad \kappa = \sum_{j=1}^m \kappa_j$$

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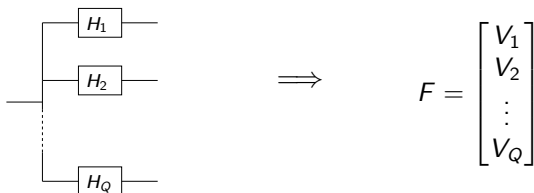
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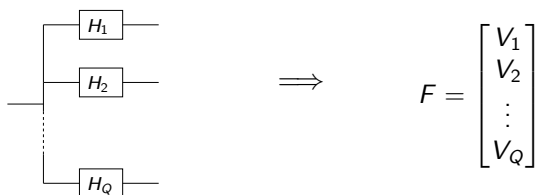
$$\kappa \left( \sum_{i=1}^n \eta_i F L_i^* L_i F^* + \kappa I \right)^{-1} = I - F \left( \sum_{i=1}^n \eta_i L_i^* L_i \right) \left( \kappa I + F^* F \left( \sum_{i=1}^n \eta_i L_i^* L_i \right) \right)^{-1} F^*$$

⇒ How can we compute efficiently  $( \cdot + F^* F )^{-1}$  ?

## Q-channel undecimated filter bank



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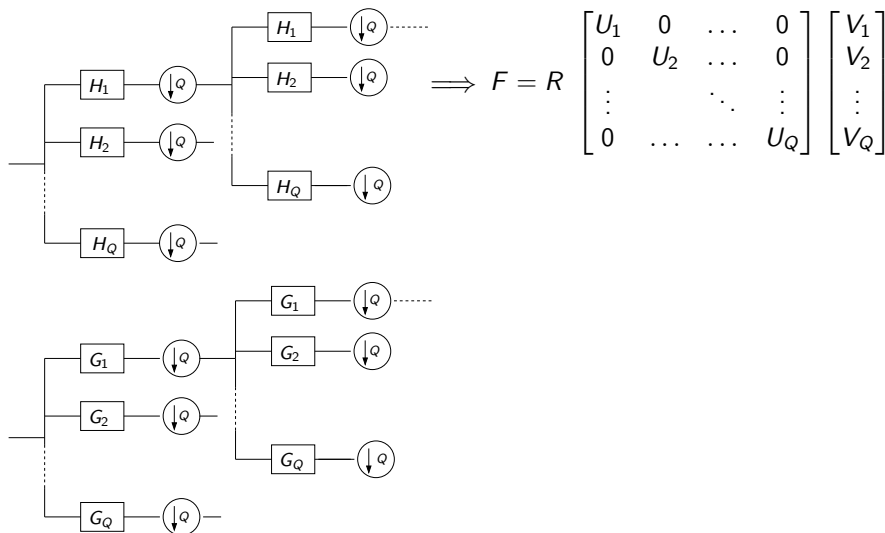


- $V_q$ : **filtering operator** such that

$$(\forall \omega \in [-\pi, \pi]^2) \quad \sum_{q=1}^Q |\hat{v}_q(\omega)|^2 \geq \mu,$$

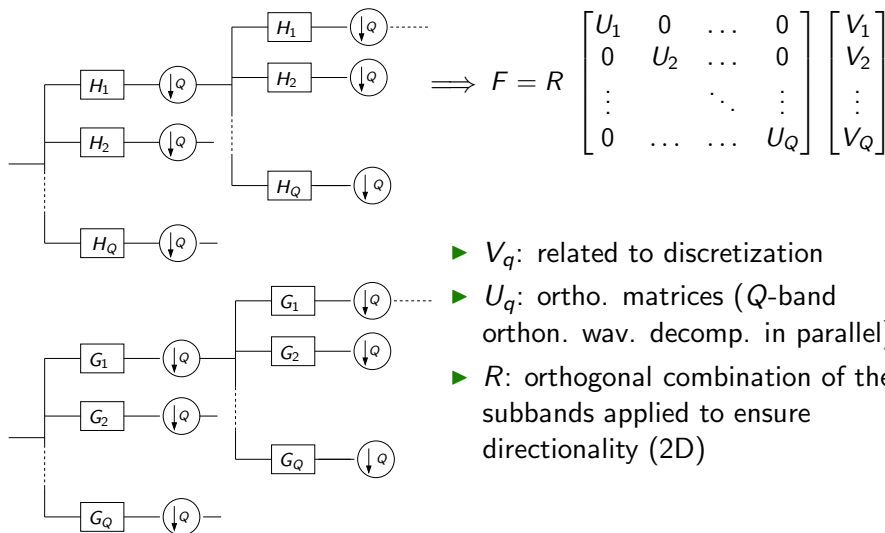
and  $\hat{v}_q(\omega)$ : frequency response of the filter associated with the convolutive operator  $V_q$ .

# Q-band DTT [Kingsbury 2001, Chaux et al. 2006]





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## A specific class of frame representation: DTT

$$F = U \begin{bmatrix} V_1 \\ V_2 \\ \vdots \\ V_Q \end{bmatrix} \quad \Rightarrow \quad F^* F = \mu_U \sum_{q=1}^Q V_q^* V_q.$$

- ▶  $U$ : tight frame analysis matrix with constant  $\mu_U \in ]0, +\infty[$ .
- ▶  $V_q$ : **prefiltering operator** such that

$$(\forall \omega \in [-\pi, \pi]^2) \quad \mu_U \sum_{q=1}^Q |\hat{v}_q(\omega)|^2 \geq \mu,$$

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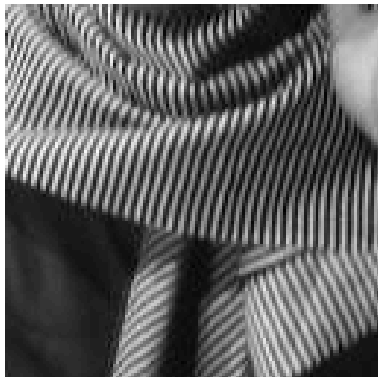
- Analysis formulation:

$$\left( \sum_{i=1}^n \eta_i L_i^* L_i + \kappa F^* F \right)^{-1} = \left( \sum_{i=1}^n \eta_i L_i^* L_i + \kappa \mu_U \sum_{q=1}^Q V_q^* V_q \right)^{-1}$$

- Synthesis formulation:

$$\begin{aligned} \text{Id} - F \left( \sum_{i=1}^n \eta_i L_i^* L_i \right) \left( \kappa \text{I} + F^* F \left( \sum_{i=1}^n \eta_i L_i^* L_i \right) \right)^{-1} F^* \\ = \text{Id} - F \left( \sum_{i=1}^n \eta_i L_i^* L_i \right) \left( \kappa \text{I} + \mu_U \sum_{q=1}^Q V_q^* V_q \left( \sum_{i=1}^n \eta_i L_i^* L_i \right) \right)^{-1} F^* \end{aligned}$$

Results: Cropped versions of Barbara image. Images are restored using SF and complex DTT



Original



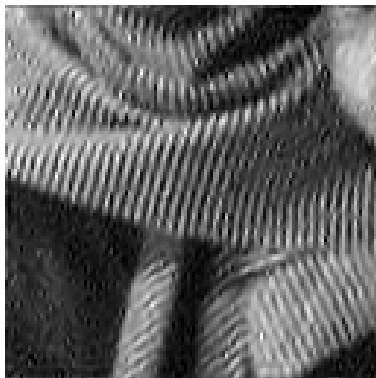
Degraded

SNR = 11.4 dB , SSIM = 0.53

## Results: Cropped versions of Barbara image. Images are restored using SF and complex DTT

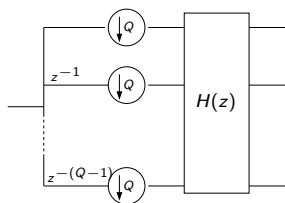


Tight-frame Complex DTT  
SNR = 13.3 dB , SSIM = 0.69



Complex DTT  
SNR = 14.2 dB , SSIM = 0.73

## Filter bank – polyphase implementation



$$\implies F = V \Pi_Q \quad \text{with} \quad V = \begin{bmatrix} V_{1,1} & \dots & V_{1,Q} \\ \vdots & & \vdots \\ V_{P,1} & \dots & V_{P,Q} \end{bmatrix}$$

- ▶  $Q \in \mathbb{N}^*$ : decimation factor.
- ▶  $P \in \mathbb{N}^*$ : number of channels.
- ▶  $P/Q \geq 1$ : redundancy introduced by such a filter bank structure.
- ▶  $\Pi_Q$ : **polyphase decomposition** from  $\ell^2(\mathbb{Z})$  to  $(\ell^2(\mathbb{Z}))^Q$ ,  
 $\Pi_Q y = (y^{(j)})_{1 \leq j \leq Q}$  where  $y^{(j)} = (y(Qn - j + 1))_{n \in \mathbb{Z}}$  is the  $j$ -th polyphase component of order  $Q$  of the signal  $y$ .
- ▶  $V_{i,j}: \ell^2(\mathbb{Z}) \rightarrow \ell^2(\mathbb{Z})$ : **SISO** (Single-Input Single-Output) stable filter.

## Filter bank – polyphase implementation

$$F = V \Pi_Q \quad \text{with} \quad \begin{bmatrix} V_{1,1} & \dots & V_{1,Q} \\ \vdots & & \vdots \\ V_{P,1} & \dots & V_{P,Q} \end{bmatrix} \quad \Rightarrow \quad F^* F = \Pi_Q^* V^* V \Pi_Q$$

## Filter bank – polyphase implementation

$$F = V \Pi_Q \quad \text{with} \quad \begin{bmatrix} V_{1,1} & \dots & V_{1,Q} \\ \vdots & & \vdots \\ V_{P,1} & \dots & V_{P,Q} \end{bmatrix} \quad \Rightarrow \quad F^* F = \Pi_Q^* V^* V \Pi_Q$$

- Analysis formulation:

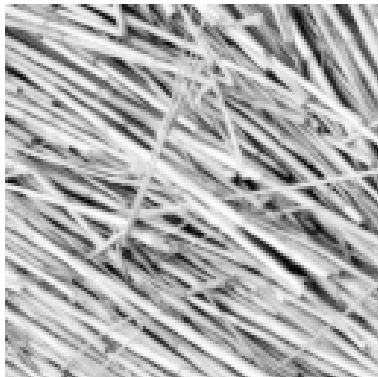
$$\left( \sum_{i=1}^n \eta_i L_i^* L_i + \kappa F^* F \right)^{-1} = \Pi_Q^* \left( \sum_{i=1}^n \eta_i W_i^* W_i + \kappa V^* V \right)^{-1} \Pi_Q$$

- Synthesis formulation:

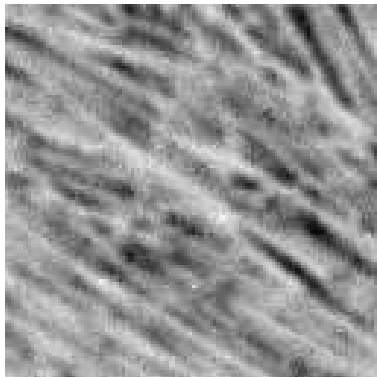
$$\begin{aligned} \text{Id} - F \left( \sum_{i=1}^n \eta_i L_i^* L_i \right) \left( \kappa \text{I} + F^* F \left( \sum_{i=1}^n \eta_i L_i^* L_i \right) \right)^{-1} F^* \\ = \text{Id} - F \Pi_Q^* \left( \sum_{i=1}^n \eta_i W_i^* W_i \right) \left( \kappa \text{I} + V^* V \left( \sum_{i=1}^n \eta_i W_i^* W_i \right) \right)^{-1} \Pi_Q F^* \end{aligned}$$



## Results: Image restored using AF with DTT and GenLOT



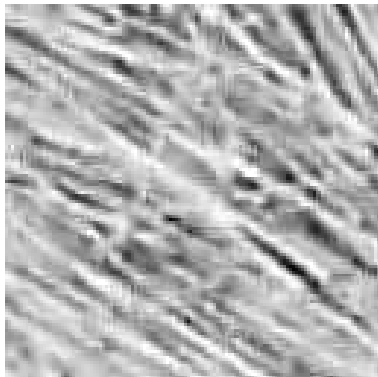
Original



Degraded

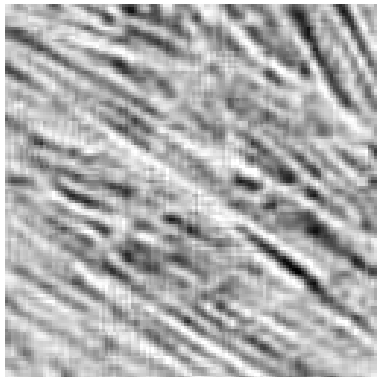
SNR = 14.8 dB , SSIM = 0.42

## Results: Image restored using AF with DTT and GenLOT



DTT

SNR = 16.7 dB , SSIM = 0.63



GenLOT

SNR = 17.1 dB , SSIM = 0.67

## Generalization

### Proposition

The operator

$$F = \Pi_R^* UV \Pi_Q$$

is a frame operator with frame constants

$$\underline{\mu} = \mu_U \inf_{\nu \in [-1/2, 1/2]} \sigma_{\min}(\nu) \quad \text{and} \quad \bar{\mu} = \mu_U \sup_{\nu \in [-1/2, 1/2]} \sigma_{\max}(\nu)$$

where, for every  $\nu$ ,  $\sigma_{\min}(\nu)$  and  $\sigma_{\max}(\nu)$  are the minimum and maximum eigenvalues of  $\widehat{\mathbf{v}}(\nu)^H \widehat{\mathbf{v}}(\nu)$ . In addition, we have:

$$F^* F = \mu_U \Pi_Q^* V^* V \Pi_Q.$$

## Conclusion

- ▶ Experimental results motivate the use of non tight frame representations.
- ▶ Allows us to deal with a large class of restoration problems with the considered class of non tight frame representations.
- ▶ Examples obtained with DTT and GenLOT but other forms of frame representations could be written as  $F = \Pi_R^* UV \Pi_D$ .