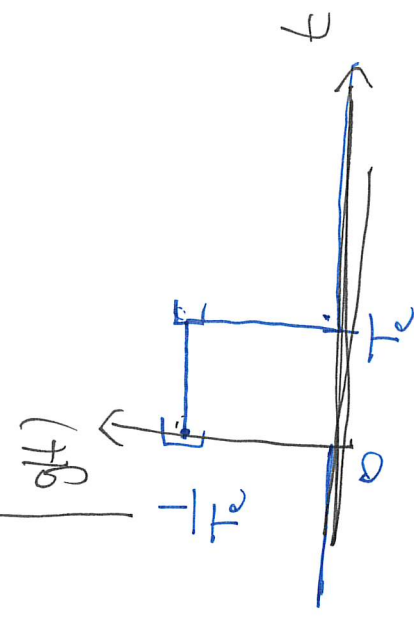
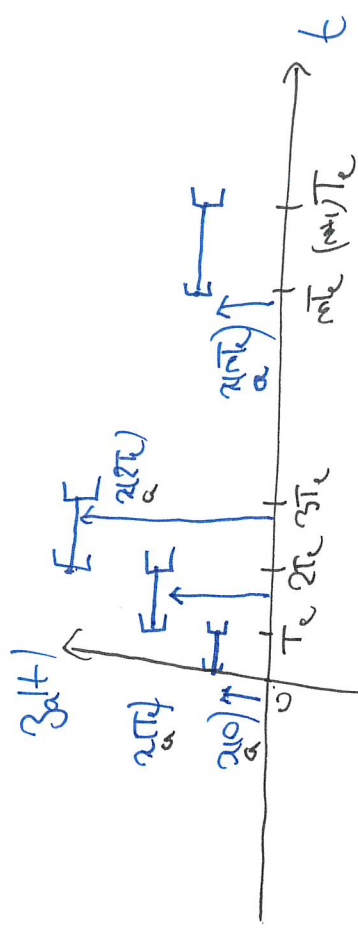
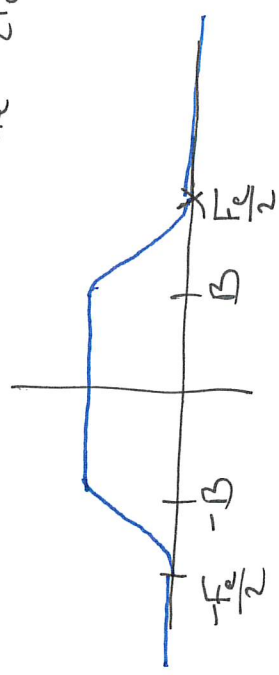


①

$$H(\beta) = 1 \quad \text{si } \beta \in [-B, B]$$

$$= 0 \quad \text{si } \beta \notin [-\frac{1}{2T_c}, \frac{1}{2T_c}]$$

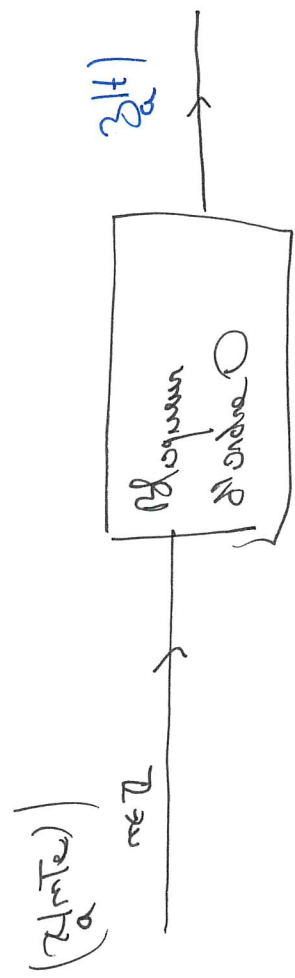


$$t \in [0, T_c], \quad Z_{\alpha}(t) = \alpha(0)$$

$$g(t - mT_c) = 0 \quad \text{si } m \neq 0$$

$$g(t) = 1/T_c, \quad \frac{1}{T_c} \cdot \alpha(0) \cdot \frac{1}{T_c} = \alpha(0)$$

$$\alpha_a(t) = T_c \sum_{m \in \mathbb{Z}} \alpha_a(mT_c) \delta(t - mT_c)$$



$$Z_{\alpha}(t) = T_c \sum_{m \in \mathbb{Z}} \alpha_a(mT_c) g(t - mT_c)$$

$$g(t) = \frac{1}{T_c} \quad \text{si } t \in [0, T_c]$$

$$= 0 \quad \text{a l'exterieur}$$

②

$$g(t) = \frac{1}{T_e}, \quad \text{sinc}(qT_e)$$

$$= 0 \quad \text{airys}$$

$$Z_{all}(t) = T_e \sum_{m \in \mathbb{Z}} x(mT_e) g(t - mT_e)$$

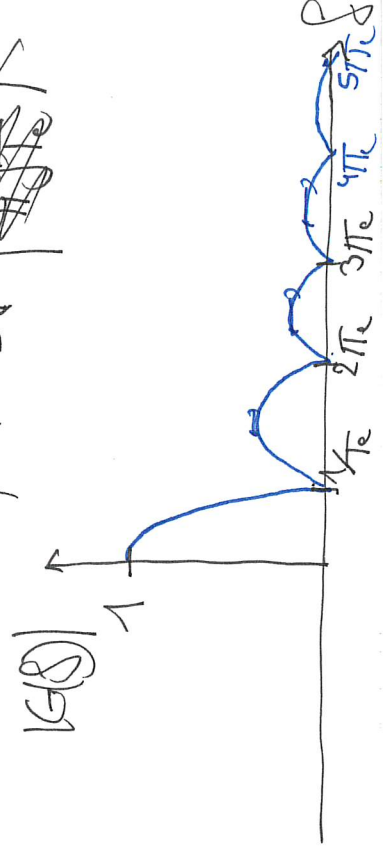
$$G(f) = \int_{-\infty}^{+\infty} g(t) e^{-2\pi i f t} dt = \int_0^{T_e} \frac{1}{T_e} e^{-2\pi i f t} dt$$

$$= \frac{1}{T_e} \times \frac{1}{2\pi i f} \left[e^{-2\pi i f t} \right]_0^{T_e}$$

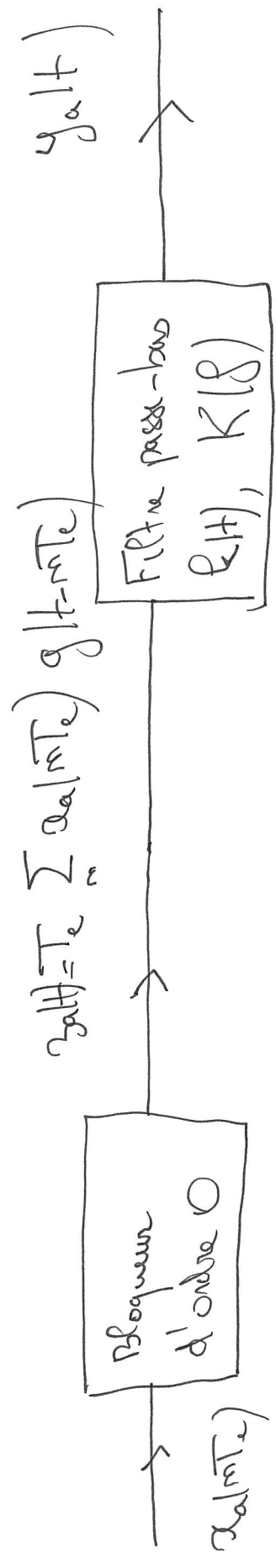
$$= \frac{1}{T_e} \times \frac{1}{2\pi i f} \left(e^{-2\pi i f T_e} - 1 \right) = \frac{1}{T_e} \frac{1}{2\pi i f} \underbrace{(1 - e^{-2\pi i f T_e})}_{\substack{\text{Euler's formula} \\ = 2i \sin \pi f T_e}}$$

$$G(f) = \frac{\sin \pi f T_e}{\pi f T_e} \cdot e^{-\pi i f T_e}$$

$$|G(f)| = \left| \frac{\sin \pi f T_e}{\pi f T_e} \right|$$



3



On peut choisir $L(f)$, ou de façon équivalente $K(f)$,

pour que $y_a(t) = x_a(t)$

Expression de $y_a(t)$?

$$y_a(t) = (p * z_a)(t), \quad p(t) = (g * l)(t)$$

$$y_a(t) = T_c \sum_k x_a[knT_c] p(t - knT_c)$$

$$y_a(t) = p * \left[T_c \sum_k x_a[knT_c] g(t - knT_c) \right](t) \quad \text{On pose } \tilde{g}_a(t) = g(t - knT_c)$$

$$y_a(t) = (p * \left[T_c \sum_k x_a[knT_c] \tilde{g}_a \right])(t) = T_c \sum_k x_a[knT_c] (p * \tilde{g}_a)(t)$$

$$(p * \tilde{g}_a)(t) ? \quad (p * \tilde{g}_a)(t) = (p * g)(t - knT_c) = p(t - knT_c)$$

5

$$(f * g_e)(t) = (f * g)(t - \tau_e)$$

$$\tilde{g}_e(t) = g(t - \tau_e)$$

$$* (f * \tilde{g}_e)(t) = (f * g)(t) = \int g(s) f(t-s) ds$$

$$\tilde{g}_e(s) = g(s - \tau_e), \quad (f * \tilde{g}_e)(t) = \int g(s - \tau_e) f(t-s) ds$$

$$u = s - \tau_e, \quad s = u + \tau_e$$

$$\int g(s - \tau_e) f(t-s) ds = \int g(u) f(t - \tau_e - u) du$$

$$= (f * g)(t - \tau_e)$$

5)

$$\left[(f \star g)(t) \right] = \left[(f \star g)(t - \varepsilon T_c) \right]$$

↗

$$K(\beta) \tilde{G}_\varepsilon(\beta)$$

$$K(\beta) G(\beta) e^{-2i\pi \int \varepsilon T_c}$$

$$g_\varepsilon(t) = g(t - \varepsilon T_c)$$

$$\tilde{G}_\varepsilon(\beta) = G(\beta) e^{-2i\pi \int \varepsilon T_c}$$

$$K(\beta) \tilde{G}_\varepsilon(\beta) = K(\beta) G(\beta) e^{-2i\pi \int \varepsilon T_c}$$

On a donc établi que

$$f(t) = (f \star g)(t)$$

$$g_\alpha(t) = (f \star g_\alpha)(t) = T_c \sum_{\varepsilon} \alpha_\varepsilon \sqrt{\varepsilon T_c} \rho(t - \varepsilon T_c)$$

(c)

$$x_a(t) = T_e \sum_n x_a(nT_e) \delta(t - nT_e), \quad H(\omega) = 1 \text{ si } \omega \in [-B, B] \\ = 0 \text{ si } |\omega| > \frac{1}{2T_e}$$

$$y_a(t) = T_e \sum_n x_a(nT_e) \delta(t - nT_e), \quad p(t) = (p * g)(t)$$

pour que $y_a(t)$ coïncide avec $x_a(t)$, il suffit que p_a

soit $p(t) = (p * g)(t)$ vérifie $L(\omega) = 1$ si $\omega \in [-B, B]$
 $= 0$ si $|\omega| > \frac{1}{2T_e}$

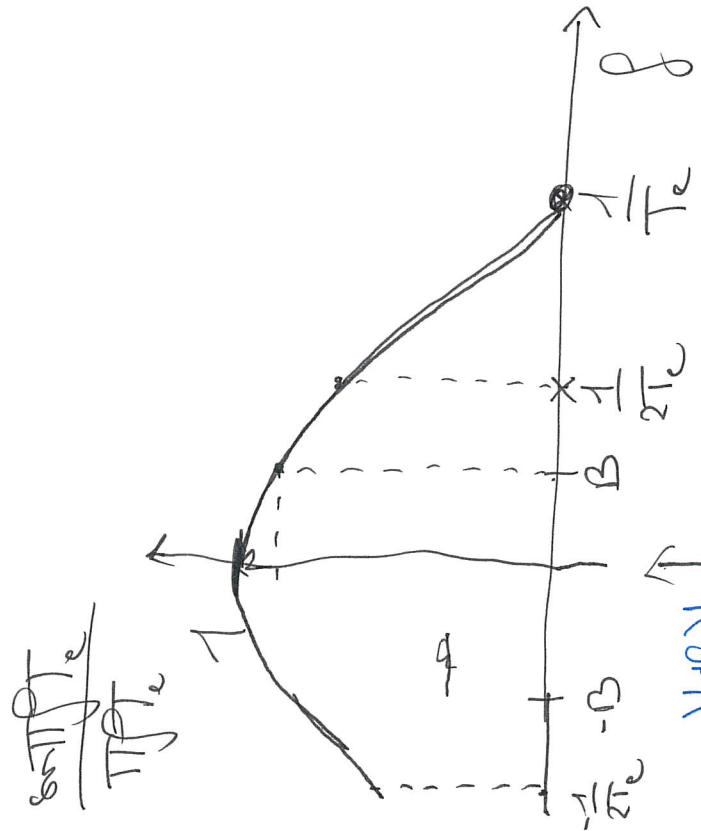
$$L(\omega) = \frac{\sin \pi \omega T_e}{\pi \omega T_e} \cdot K(\omega) = \begin{cases} 1 & \text{si } \omega \in [-B, B] \\ 0 & \text{si } |\omega| > \frac{1}{2T_e} \end{cases}$$

$$K(\omega) = 0 \text{ si } |\omega| > \frac{1}{2T_e}, \quad K(\omega) = \frac{1}{G(\omega)} = e^{i\pi \omega T_e} \frac{\pi \omega T_e}{\sin \pi \omega T_e} \text{ si } \omega \in [-B, B]$$

(7)

$$k(\beta) = 0 \text{ si } |\beta| > \frac{1}{2T_c}$$

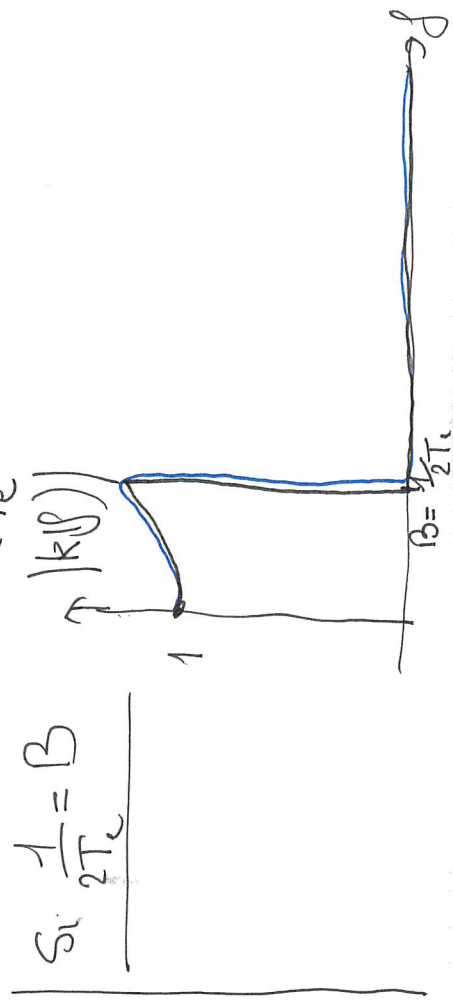
$$k(\beta) = \frac{i\pi\beta T_c}{\sin \pi\beta T_c}$$



$$|k(\beta)| = \frac{1}{\left| \frac{\sin \pi\beta T_c}{\pi\beta T_c} \right|} \text{ si } \beta \in [-B, B]$$

$$\left(\frac{\sin \pi\beta T_c}{\pi\beta T_c} \right) = \frac{\sin \frac{\pi}{2}}{\frac{\pi}{2}} = \frac{2}{\pi}$$

$$\text{si } \frac{1}{2T_c} = B$$



$$H(s) = H_a(s F_e)$$

$$H(s) = \sum_k h_k e^{-2j\pi k s}$$

Que vaut h_k

Si on est fixé,

pour tout n ?

$$h_k = \int_{-1/2}^{1/2} H(s) e^{2j\pi k s} ds$$

$$= \int_{-1/2}^{1/2} \left(\sum_k h_k e^{-2j\pi k s} \right) e^{2j\pi k s} ds$$

$$= \sum_k h_k \int_{-1/2}^{1/2} e^{-2j\pi (n-k)s} ds$$

$$= \sum_k h_k$$

$H_a(s)$ Fonction de transfert du filtre analogique

$h_k(t)$ la réponse impulsionnelle.

$$\int_{-1/2}^{1/2} e^{-2j\pi (n-k)s} ds = \begin{cases} 1 & \text{si } n=k \\ 0 & \text{si } n \neq k \end{cases}$$

si $n \neq k$, $\int_{-1/2}^{1/2} e^{-2j\pi (n-k)s} ds = 0$

9

$$P_{\text{rms}} = \int_{-\frac{1}{2}}^{\frac{1}{2}} H(f) e^{2i\pi mf} df$$

$$\omega = 2\pi f$$

$$S = \frac{\omega}{T_c} = 2\pi T_c$$

$$df = T_c d\omega$$

or

$$H(f) = H_a(S T_c)$$

$$\Rightarrow P_{\text{rms}} = T_c P_a(m T_c)$$

$$= \int_{-\frac{1}{2}}^{\frac{1}{2}} H_a(S T_c) e^{2i\pi mf} df$$

$$= T_c \int_{-\frac{f_c}{2}}^{\frac{f_c}{2}} H_a(\omega) e^{2i\pi m T_c \omega} d\omega$$

$$= T_c \int_{-\infty}^{+\infty} H_a(\omega) e^{2i\pi m T_c \omega} d\omega$$

$$P_a(m T_c)$$

10

